

$$\mu=\mu^\Theta+RTln\frac{P}{P^\Theta}$$

$$\mu_A(l)=\mu^{\circ}_A(l)+RTlnX_A$$

$$\Delta T_v=K_em \qquad K_e=\tfrac{RM_A(T_v^{\circ})^2}{\Delta H_{izp}}$$

$$\Delta T_z=K_km \qquad K_k=\tfrac{RM_A(T_z^{\circ})^2}{\Delta H_{tal}}$$

$$\pi =icRT$$

$$v=\frac{1}{v_i}\frac{dc_i}{dt}$$

$$-\frac{dc}{dt}=k_nc^n$$

$$ln\frac{c}{c_0}=-k_1t \quad \tau=\frac{ln2}{k_1}$$

$$c=c_0-k_0t \quad \tau=\frac{c_0}{2k_0}$$

$$\frac{1}{c^{n-1}}=\frac{1}{c_0^{n-1}}+(n-1)k_nt \qquad \tau=\frac{2^{n-1}-1}{(n-1)k_nc_0^{n-1}}$$

$$k=Ae^{-E_a/RT}$$

$$\Delta G^\ominus=-RTlnK_P \qquad \Delta G^\ominus=v_C\mu_C^\ominus+v_D\mu_D^\ominus-v_A\mu_A^\ominus-v_B\mu_B^\ominus \qquad K_P=\frac{P_C^{v_C}P_D^{v_D}}{P_A^{v_A}P_B^{v_B}}$$

$$K_X=K_PP^{-\Delta\nu} \qquad \qquad K_X=\frac{x_C^{v_C}x_D^{v_D}}{x_A^{v_A}x_B^{v_B}} \qquad \qquad \Delta\nu=v_C+v_D-v_A-v_B$$

$$K_c=K_P(RT)^{-\Delta\nu} \qquad K_c=\frac{c_C^{v_C}c_D^{v_D}}{c_A^{v_A}c_B^{v_B}}$$

$$ln\frac{K_P(T_2)}{K_P(T_1)}=-\frac{\overline{\Delta H^\ominus}}{R}\Big(\frac{1}{T_2}-\frac{1}{T_1}\Big)$$